

# Modélisation et analyse de systèmes biologiques hybrides par les mesures d'occupations

Alexandre Rocca<sup>1,2</sup>, Marcelo Forets<sup>1</sup>, Victor Magron<sup>1</sup>,  
Thao Dang<sup>1</sup>, Eric Fanchon<sup>2</sup>

<sup>1</sup>Verimag, <sup>2</sup>TIMC-IMAG, Grenoble

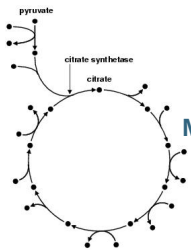
June 18, 2018

## Context

- Biological systems

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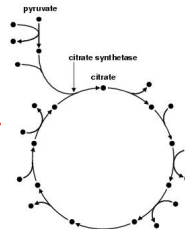
➤ Biological systems



Molecular level

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➤ Biological systems



Molecular level



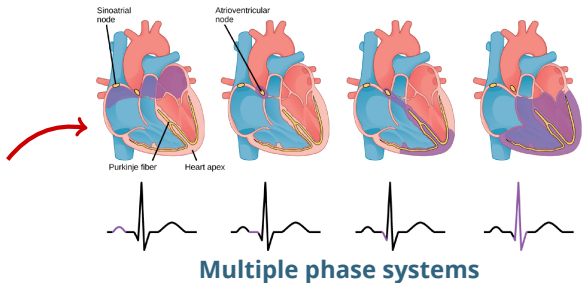
Population level

## Context

- Biological systems
- Multi-stage behaviours

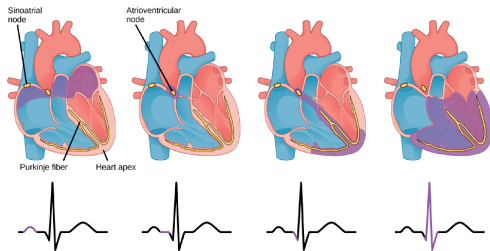
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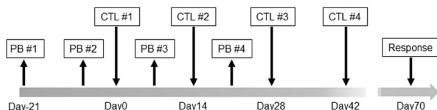


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- Biological systems
- Multi-stage behaviours



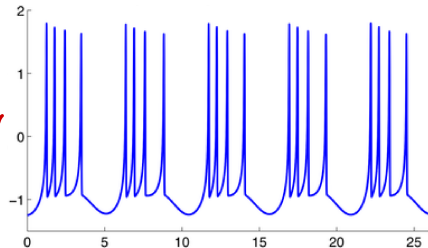
### Multiple phase systems



### Experimental protocols

## Context

- Biological systems
- Multi-stage behaviours
- Slow/fast dynamics



Multiple time scale systems

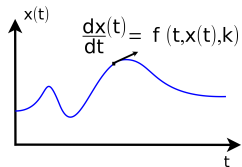


## Context

- Biological systems
- Multi-stage behaviours
- Slow/fast dynamics
- 👉 Temporal evolution

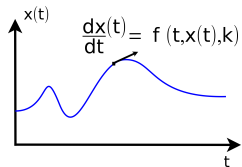
## Modelling

- Continuous Time
  - Ordinary differential equations (ODEs)



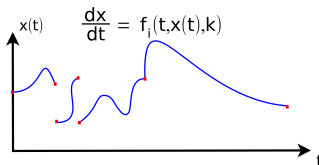
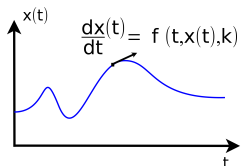
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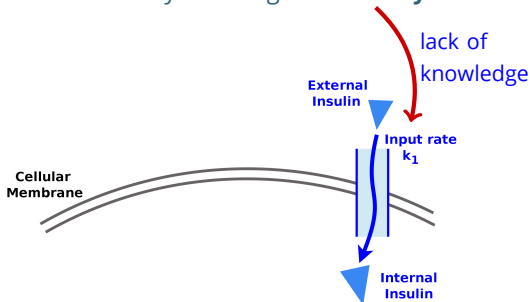
## Modelling

- Continuous Time
  - Ordinary differential equations (ODEs)
  
- Hybrid dynamics
  - Hybrid dynamical systems



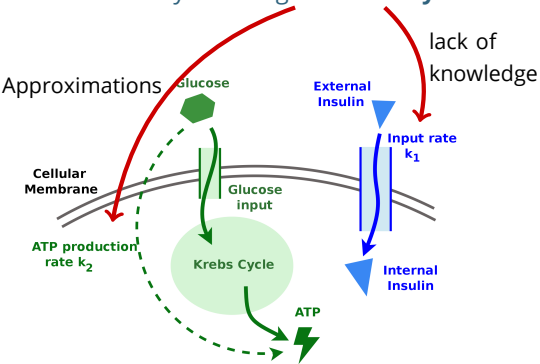
## Formal methods

- Efficiently handling **uncertainty** and **variability**



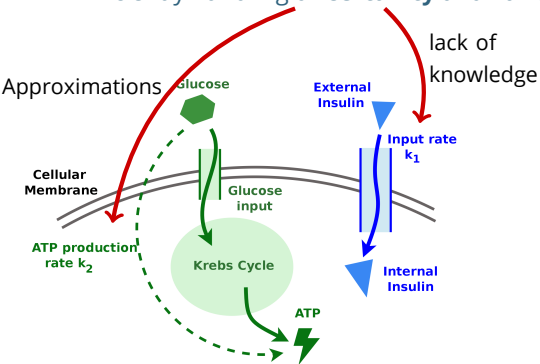
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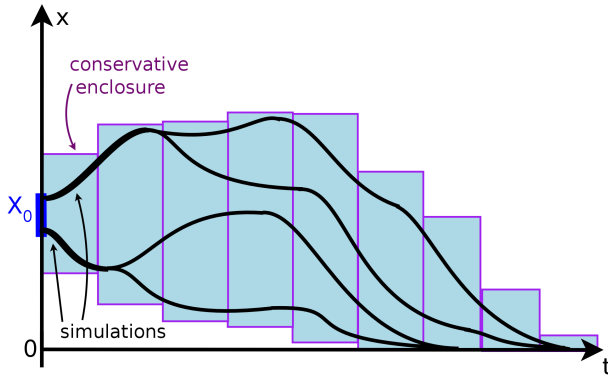
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## Formal methods

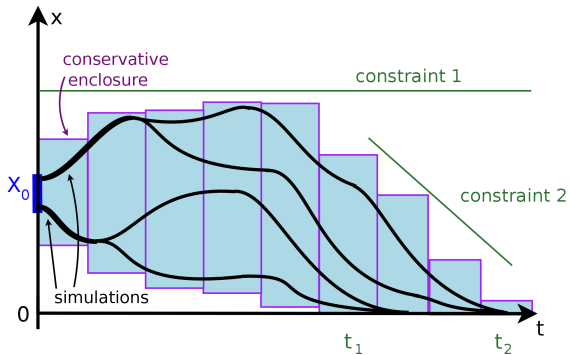
- Efficiently handling **uncertainty** and **variability**
- Providing **set-based** analysis





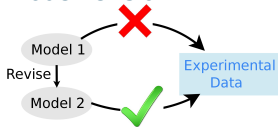
## Formal methods

- Efficiently handling **uncertainty** and **variability**
- Providing **set-based** analysis
- Proving requirements and validating hypothesis



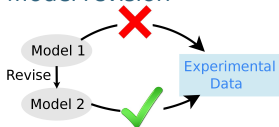
# Contributions

## 1. Model revision



## Contributions

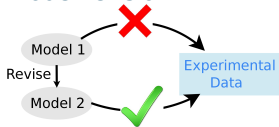
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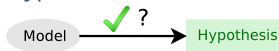
- Optimal control method based on occupation measures
  - Haemoglobin production model

## Contributions

### 1. Model revision



### 2. Hypothesis validation

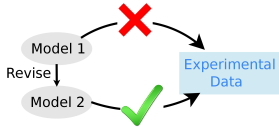


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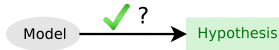
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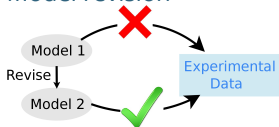
- Haemoglobin production model

- Set-based analysis using Bernstein expansion or Krivine-Stengle representations

- Iron homeostasis model

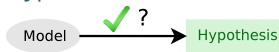
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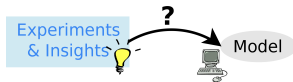
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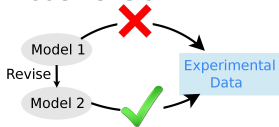
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### 3. Model design



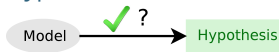
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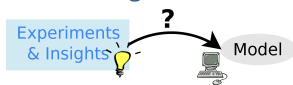
- ☞ Optimal control method based on occupation measures
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### 2. Hypothesis validation



- ☞ Set-based analysis using Bernstein expansion or Krivine-Stengle representations
  - Iron homeostasis model

### 3. Model design



- ☞ Hybrid automata to model experimental protocols
  - Haemoglobin production model
  - Generational Cadmium absorption study

# Biological hybrid model revision using occupation measures



# The Haemoglobin production model

- Erythroblasts: Differentiating red blood cells in bone marrow

## The Haemoglobin production model

- Erythroblasts: Differentiating red blood cells in bone marrow
- Model of Haemoglobin production during the last 52 hours

- ODE system  $\mathcal{F}_{norm}$

$$\left\{ \begin{array}{l} \frac{dFe}{dt} = k_1 Fe_{ex} - k_2 Fe - k_3 Fe \\ \frac{dH}{dt} = k_3 Fe - k_4 H - 4 k_5 H \cdot G \\ \frac{dG}{dt} = k_6 H - 4 k_5 H \cdot G - k_7 G \\ \frac{dHb}{dt} = k_5 H \cdot G - k_8 Hb \end{array} \right.$$

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### • Intra cellular Iron: Fe

$\text{Fe}_{ex} \rightarrow \text{Fe}$ , Iron input rate:  $k_1$

$\text{Fe} \rightarrow \emptyset$ , Iron degradation rate:  $k_2$

- ODE system  $\mathcal{F}_{norm}$

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Fe  $\rightarrow$  H, Heme production rate:  $k_3$

H  $\rightarrow$   $\emptyset$ , Heme degradation rate:  $k_4$

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• **Intra cellular (free) Heme:** H

• **Intra cellular Globin:** G

→ G, Globin production rate:  $k_6$

(accelerated by Heme)

G → ∅, Globin degradation rate:  $k_7$

• ODE system  $\mathcal{F}_{norm}$

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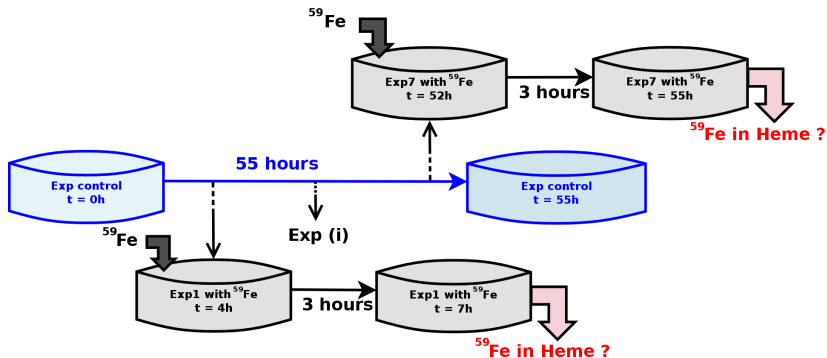
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- **Intra cellular Iron:** Fe
  - **Intra cellular (free) Heme:** H
  - **Intra cellular Globin:** G
  - **Intra cellular Haemoglobin:** Hb
- $4G + 4H \rightarrow \text{Hb}$ , Haemoglobin production rate:  $k_5$
- $\text{Hb} \rightarrow \emptyset$ , Haemoglobin degradation rate:  $k_8$

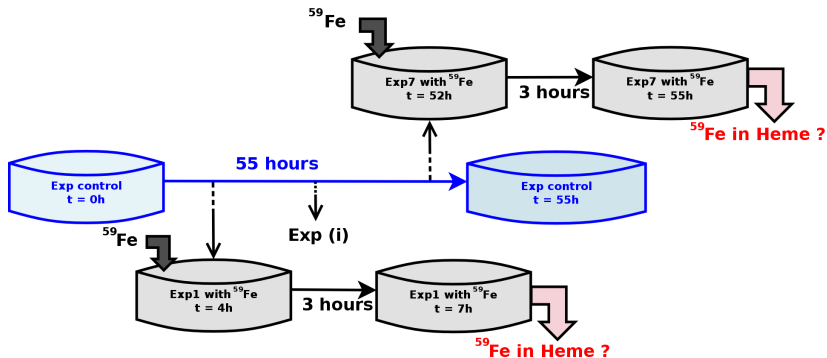
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## Associated experimental protocol

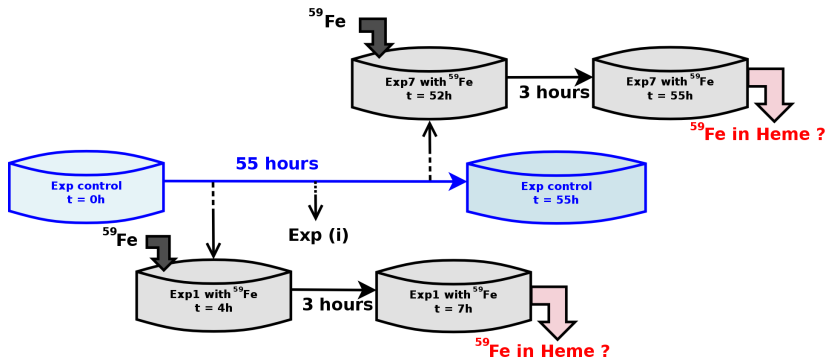


## Associated experimental protocol



👉 ~ Integration speed of iron in heme

## Associated experimental protocol



- ☞  $\sim$  Integration speed of iron in heme
- ☞  $\sim$  Heme mainly in haemoglobin

## Introducing new variables

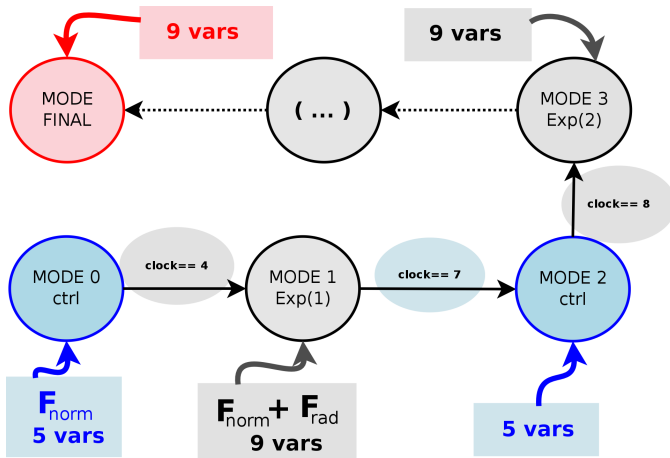
- $\mathcal{F}_{norm}$  : System without radioactive species

$$\left\{ \begin{array}{l} \frac{dFe}{dt} = k_1 Fe_{ex} - k_2 Fe - k_3 Fe \\ \frac{dH}{dt} = k_3 Fe - k_4 H - 4k_5 H \cdot G \\ \frac{dG}{dt} = k_6 H - 4k_5 H \cdot G - k_7 G \\ \frac{dHb}{dt} = k_5 H \cdot G - k_8 Hb \end{array} \right.$$

- $\mathcal{F}_{rad}$  : System with (additional) radioactive species.

$$\left\{ \begin{array}{l} \dots = \dots \\ \frac{d^{59}Fe}{dt} = k_1 {}^{59}Fe_{ex} - k_2 {}^{59}Fe - k_3 {}^{59}Fe \\ \frac{d^{59}H}{dt} = k_3 {}^{59}H - k_4 {}^{59}H - 4k_5 {}^{59}H \cdot G_{rad} \\ \frac{dG_{rad}}{dt} = k_6 ({}^{59}H + H) - 4k_5 ({}^{59}H + H) G_{rad} - k_7 G_{rad} \\ \frac{d^{59}Hb}{dt} = k_5 {}^{59}H \cdot G_{rad} - k_8 {}^{59}Hb \end{array} \right.$$

## Associated hybrid automaton



# Model revision: Haemoglobin model

## We have:

- A hybrid automaton modelling a protocol



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### We have:

- A hybrid automaton modelling a protocol
- A parameter set obtained using simulations [Bouchnita et al., 2016]

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### Our approach:

- ☞ Transform a constant parameter into a time varying law

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  - In the haemoglobin production model:  $k_3 \Rightarrow k_3(t)$

$$\frac{dH}{dt} = k_3 \text{Fe} - k_4 H - 4k_5 H G$$

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- 👉 Transform a constant parameter into a time-varying law
  - In the haemoglobin production model:  $k_3 \Rightarrow k_3(t)$

$$\frac{dH}{dt} = \underbrace{k_3}_{\text{Iron integration rate}} \text{Fe} - k_4 H - 4k_5 H G$$

Iron integration rate

## Model revision: Haemoglobin model

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- A parameter set obtained using simulations [Bouchnita et al., 2016]

### We want:

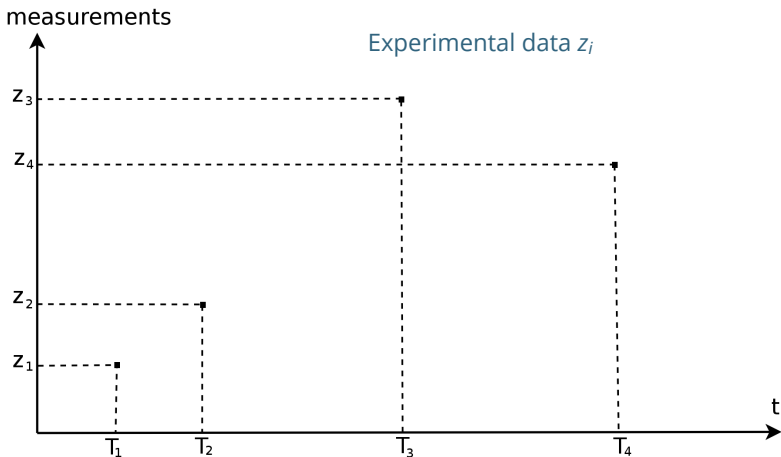
- To better reproduce the datasets

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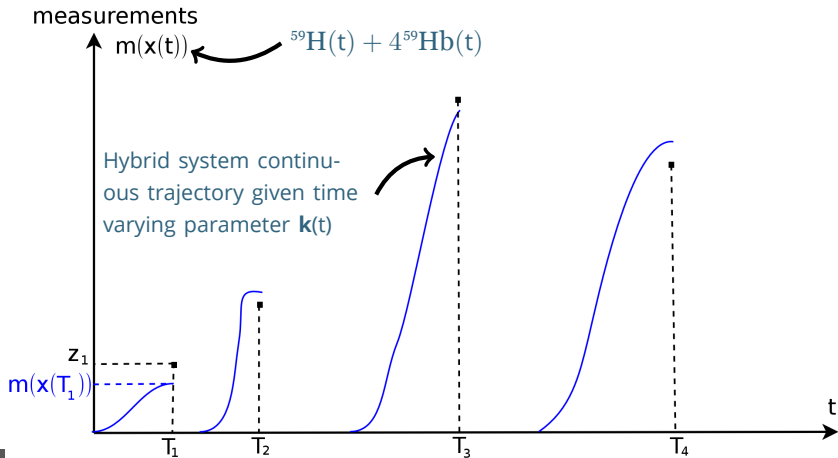
- ☞ Transform a constant parameter into a time varying law
  - In the haemoglobin production model:  $k_3 \Rightarrow k_3(t)$

$$\frac{dH}{dt} = k_3(t)Fe - k_4H - 4k_5HG$$

## Model revision: Cost function

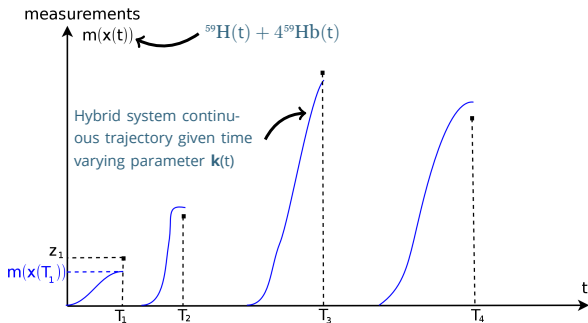


## Model revision: Cost function





## Model revision: Cost function



➤ We search for  $\mathbf{k}(t)$  minimizing:

$$\sum_{j=1}^{n_{exp}} \|\mathbf{m}(\mathbf{x}(T_j)) - \mathbf{z}_j\|$$

## Model revision: Optimization problem

$$\triangleright \min_{(\mathbf{x}, \mathbf{k})} \sum_{j=1}^{n_{exp}} \|\mathbf{m}(\mathbf{x}(T_j, \mathbf{k}(T_j))) - \mathbf{z}_j\|$$

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↳  $\mathbf{x}(t, \mathbf{k}(t))$  trajectory of a hybrid system

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➤ Optimal control problem (OCP)

# The OCP method motivations

We want to solve an OCP with:



# The OCP method motivations

We want to solve an OCP with:

- Hybrid dynamical system

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We want to solve an OCP with:

- Hybrid dynamical system
- Polynomial continuous dynamics

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## The OCP method motivations

### We want to solve an OCP with:

- Hybrid dynamical system
  - Polynomial continuous dynamics
  - Dimension varying between two modes
  - Cost function on intermediate time points
- 
- ☞ An appropriate approach using occupation measures reformulation
    - [Zhao et al., 2017]
  - ☞ Do not rely on sampling and numerous simulations

# Measure intuition

## Examples of measure:

- Volume (Lebesgue measure)
- Density measure
- Probability measure, ...

## Occupation Measure Intuition

$$\dot{\mathbf{x}} = f(\mathbf{x}(t))$$

Occupation measure of  $A \subset X$ :

$$\mu(A|\mathbf{x}_0) := \int_0^T I_A(\mathbf{x}(t|\mathbf{x}_0)) dt,$$

➤ **Indicator function:**  $I_A(\mathbf{x}(t|\mathbf{x}_0)) = 1$  if  $\mathbf{x}(t|\mathbf{x}_0) \in A$  else 0

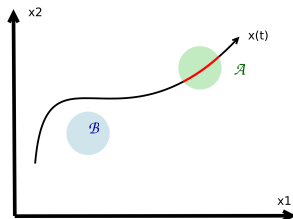
## Occupation Measure Intuition

$$\dot{\mathbf{x}} = f(\mathbf{x}(t))$$

Occupation measure of  $A \subset X$ :

$$\mu(A|\mathbf{x}_0) := \int_0^T l_A(\mathbf{x}(t|\mathbf{x}_0)) dt,$$

➤ Indicator function:  $l_A(\mathbf{x}(t|\mathbf{x}_0)) = 1$  if  $\mathbf{x}(t|\mathbf{x}_0) \in A$  else 0





## Occupation Measure Intuition

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**Occupation measure** of  $A \subset X$ :

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- **Indicator function:**  $l_A(\mathbf{x}(t|\mathbf{x}_0)) = 1$  if  $\mathbf{x}(t|\mathbf{x}_0) \in A$  else 0
- occupation measure  $\mu(\cdot|\mathbf{x}_0)$  on  $A$ : time spent by a trajectory  $\mathbf{x}(t|\mathbf{x}_0)$  in  $A$ 
  - [Lasserre et al., 2008]
- The support of  $\mu(\cdot|\mathbf{x}_0)$  is the trajectory in  $X$

## Liouville Equation

- Given an uncertain initial condition  $X_0$  and final set  $X_T$
- and associated initial and final measures  $\mu_0$  and  $\mu_T$ :

- $\mu_0$  models the initial condition distribution

- $\mu_T = \int_X l_{X_T}(\mathbf{x}(T|\mathbf{x}_0)) d\mu_0$

$$\nabla \cdot (f\mu) = \mu_T - \mu_0$$

- Occupation measure Liouville equation
- Linear equation of the evolution of the occupation measure
- $\mathcal{L}'_f \mu = \nabla \cdot (f\mu)$  : divergence of the measure under the effect of the vector field  $f$

## Liouville Intuition

- $\dot{\mathbf{x}} = f(\mathbf{x}(t))$
- $\mathbf{x}(0) \in X_0$
- $\mathbf{x}(T) \in X_T$
- $\mathcal{L}'_f \mu = \mu_T - \mu_0$
- $\mu, \mu_0, \mu_T \geq 0$
- $X_0, X_T$ : supports of  $\mu_0, \mu_T$

- ☞ Non-linear and differential constraint system on the phase space ...
- ☞ **Transformed into an infinite linear system** on the measure space

# Hybrid Liouville

➤ Measure of **initial condition in mode  $i$** :  $\mu_0^i$

## Hybrid Liouville

- Measure of **initial condition in mode  $i$** :  $\mu_0^i$
- **Evolution of the occupation measure** with flow  $f_i$ :  $\mathcal{L}_i^t \mu^i$

## Hybrid Liouville

- Measure of **initial condition in mode  $i$** :  $\mu_0^i$
- **Evolution of the occupation measure** with flow  $f_i$ :  $\mathcal{L}'_i \mu^i$
- Measure of **trajectories entering the mode  $i$** :  $R_{(j,i)} \mu^{S_{j,i}}$ 
  - affected by a reset map associated with the transitions

## Hybrid Liouville

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## Hybrid Liouville

- Measure of **initial condition in mode  $i$** :  $\mu_0^i$
- **Evolution of the occupation measure** with flow  $f_i$ :  $\mathcal{L}_i' \mu^i$
- Measure of **trajectories entering the mode  $i$** :  $R_{(j,i)} \mu^{S_{j,i}}$ 
  - affected by a reset map associated with the transitions
- Measure of **trajectories in mode  $i$  at final time  $T$** :  $\mu_T^i$
- Measure of **trajectories leaving mode  $i$** :  $\mu^{S_{i,j}}$



## Hybrid Liouville

- Measure of **initial condition in mode  $i$** :  $\mu_0^i$
- **Evolution of the occupation measure** with flow  $f_i$ :  $\mathcal{L}'_i \mu^i$
- Measure of **trajectories entering the mode  $i$** :  $R_{(j,i)} \mu^{S_{j,i}}$ 
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$$\mu_0^i + \mathcal{L}'_i \mu^i + \sum_{(j,i) \in \mathcal{E}} R_{(j,i)} \mu^{S_{j,i}} = \mu_T^i + \sum_{(i,j) \in \mathcal{E}} \mu^{S_{i,j}}$$

## Optimal control solution

- Reformulation as an infinite dimensional linear optimisation problem
- Existing converging approximations using semi-definite programming relaxations
  - A control function  $\mathbf{u}_i(t)$  associated to each mode (dynamics)
  - Each  $\mathbf{u}_i(t)$  approximated by polynomials
  - For only one final time  $T$

## HOCP method: discussion

### Advantages:

- Converge to the optimum

### Limitations:

- Do not handle cost at fixed intermediate time
- Cannot be used in a dynamic programming scheme
- Piecewise polynomial control

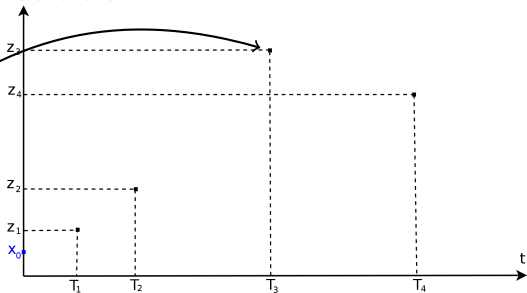
### Our proposal:

- 👉 HOCP applied in a greedy algorithm
- 👉 Smoothing of the control needed

## The model revision algorithm

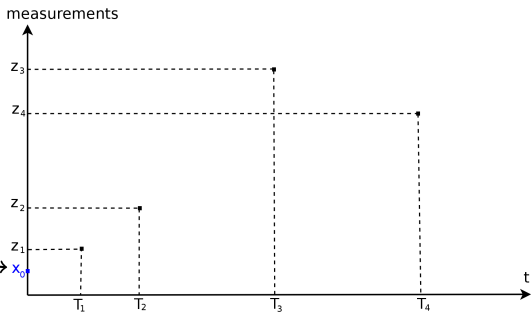
➤ A set of data points  $(z_j, T_j)$

measurements



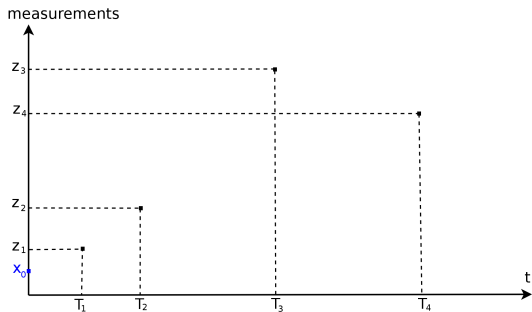
## The model revision algorithm

- A set of data points  $(z_j, T_j)$
- An initial condition  $\mathbf{x}_0$



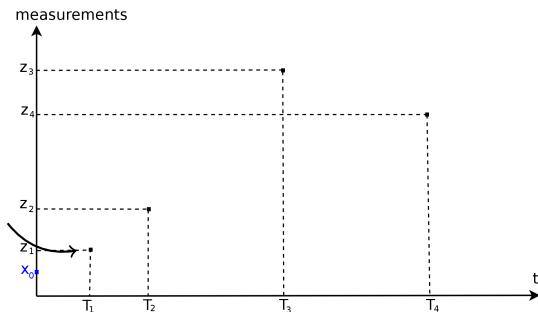
## The model revision algorithm

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- Apply [Zhao et al., 2017] method with:



## The model revision algorithm

- A set of data points  $(z_j, T_j)$
- An initial condition  $\mathbf{x}_0$
- Apply [Zhao et al., 2017] method with:
  - Final time  $T = T_1$
  - cost to minimize:  $H(T_1, \mathbf{x}(T_1), \mathbf{u}(T_1))$

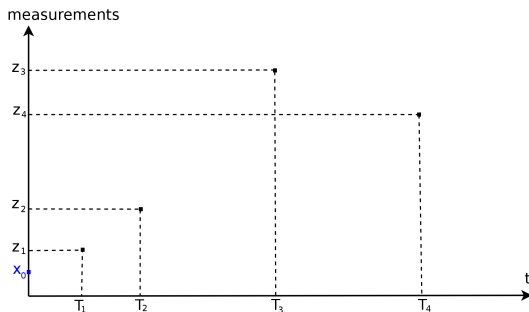


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☞ Haemoglobin model:

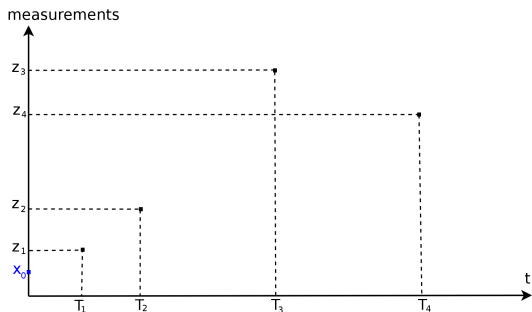
$$({}^{59}\text{H}(T_1) + 4{}^{59}\text{Hb}(T_1) - z_1)^2$$





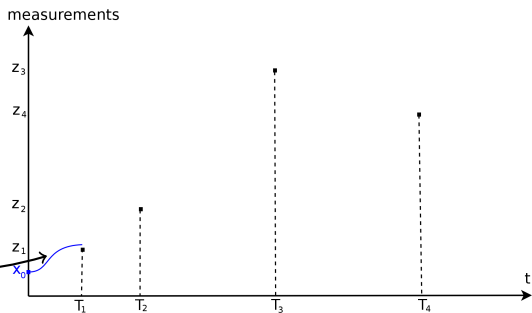
## The model revision algorithm

- A set of data points  $(z_j, T_j)$
- An initial condition  $\mathbf{x}_0$
- Apply [Zhao et al., 2017] method with:
  - Final time  $T = T_1$
  - cost to minimize:  $H(T_1, \mathbf{x}(T_1), \mathbf{u}(T_1))$
  - control  $\mathbf{u}_{[0, T_1]}(t)$  Piecewise polynomial



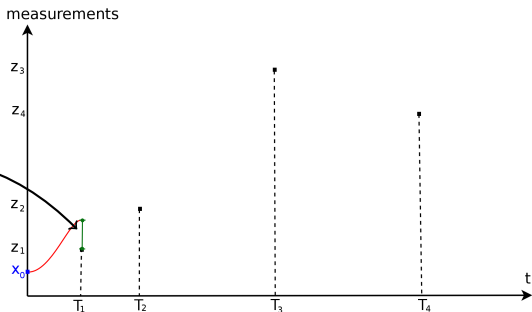
## The model revision algorithm

- Given  $\mathbf{u}_{[0, T_1]}(t)$
- 🔧 Simulate and get  $\|\mathbf{m}(\mathbf{x}(T_1)) - \mathbf{z}_1\|$



## The model revision algorithm

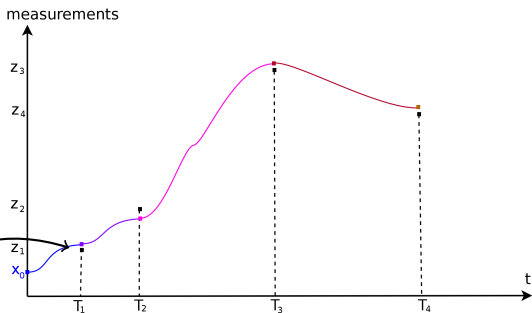
- Given  $\mathbf{u}_{[0, T_1]}(t)$ 
  - ⊞ Simulate and get  $\|\mathbf{m}(\mathbf{x}(T_1)) - \mathbf{z}_1\|$
- If not accurate enough:
  - ⊞ Increase polynomial degree



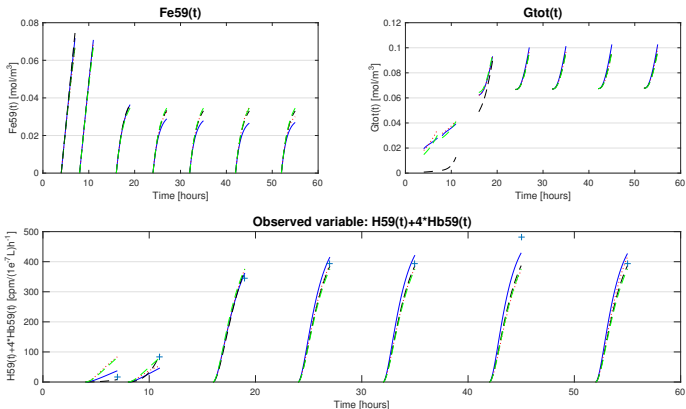
## The model revision algorithm

- A set of data points  $(z_j, T_j)$
- An initial condition  $\mathbf{x}_0$
- Apply [Zhao et al., 2017] method with:
  - Final time  $T = T_1$
  - cost to minimize:  $H(T_1, \mathbf{x}(T_1), \mathbf{u}(T_1))$
  - control  $\mathbf{u}_{[0, T_1]}(t)$  Piecewise polynomial
- Given  $\mathbf{u}_{[0, T_1]}(t)$ 
  - ☞ Simulate and get  $\|\mathbf{m}(\mathbf{x}(T_1)) - \mathbf{z}_1\|$
- New initial condition:  $\mathbf{x}(T_1)$

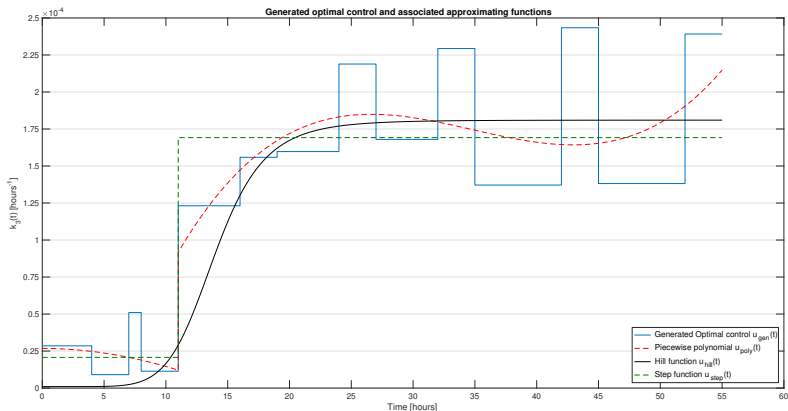
Loop



## Results on Haemoglobin case study



## Results on Haemoglobin case study



## Results on Haemoglobin case study

### Implementation in Matlab

Control Type	$\varepsilon_{total}$
Sampling method [Bouchnita et al., 2016]	0.23
Generated control	0.096
Step function fit	0.12
Piecewise Polynomial fit	0.13
Hill function fit	0.075

$$\varepsilon_{total} = \sum_{1 \leq j \leq n_{exp}} \frac{\sqrt{H(\mathbf{x}(T_j))}}{\sum_{1 \leq j \leq n_{exp}} z_j}.$$

## Conclusion

- ☞ Model revision of hybrid systems
  - Good trade-off performance/accuracy
  - Do not rely on numerous simulations

### Future work:

- ☞ Synthesising sets of valid parameters for biological hybrid systems
  - Occupation measure formulation for parameter synthesis






**Thank you for your attention !**




## Publications

- *Multi-scale Modelling of Erythropoiesis and Hemoglobin Production*, Journal of Inorganic and Organometallic Polymers and Materials, [Bouchnita et al., 2016]
- *Application of the Reachability Analysis for the Iron Homeostasis Study*, HSB2016, [Rocca et al., 2016]
- *Certified Roundoff Error Bounds using Bernstein Expansions and Sparse Krivine-Stengle Representations*, ARITH24 [Rocca et al., 2017b]
- *Occupation measure methods for modelling and analysis of biological hybrid systems*, ADHS2018, [Rocca et al., 2017a]
- *Certified Roundoff Error Bounds using Bernstein Expansions and Sparse Krivine-Stengle Representations*, submitted to Transaction on Computers [Magron et al., 2018]


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-  Bouchnita, A., Rocca, A., Fanchon, E., Koury, M., Moulis, J., and Volpert, V. (2016).  
Multi-scale modelling of erythropoiesis and hemoglobin production.  
*Journal of Inorganic and Organometallic Polymers and Materials*,  
26(6):1362–1379.
-  Lasserre, J. B., Henrion, D., Prieur, C., and Trélat, E. (2008).  
Nonlinear optimal control via occupation measures and lmi-relaxations.  
*SICON*.
-  Magron, V., Rocca, A., and Dang, T. (2018).  
Certified roundoff error bounds using bernstein expansions and sparse  
krivine-stengle representations.  
*arXiv preprint arXiv:1802.04385*.

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-  Rocca, A., Dang, T., Fanchon, E., and Moulis, J.-M. (2016). Application of the reachability analysis for the iron homeostasis study. In *International Workshop on Hybrid Systems Biology*, pages 67–84. Springer.
-  Rocca, A., Forets, M., Magron, V., Fanchon, E., and Dang, T. (2017a). Occupation measure methods for modelling and analysis of biological hybrid automata. *arXiv preprint arXiv:1710.03158*.
-  Rocca, A., Magron, V., and Dang, T. (2017b). Certified roundoff error bounds using bernstein expansions and sparse krivine-stengle representations. In *Computer Arithmetic (ARITH), 2017 IEEE 24th Symposium on*, pages 74–81. IEEE.

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-  Zhao, P., Mohan, S., and Vasudevan, R. (2017).  
Optimal control for nonlinear hybrid systems via convex relaxations.  
*arXiv preprint arXiv:1702.04310.*